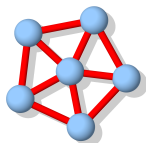


# Tackling Neural Network Expressivity via (virtual Newton) Polytopes

Christoph Hertrich



IOL & DISCOGA Research Seminar  
May 11, 2021

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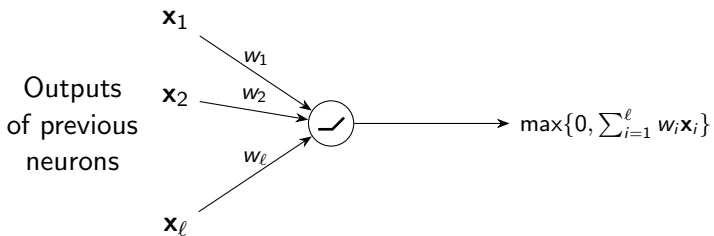
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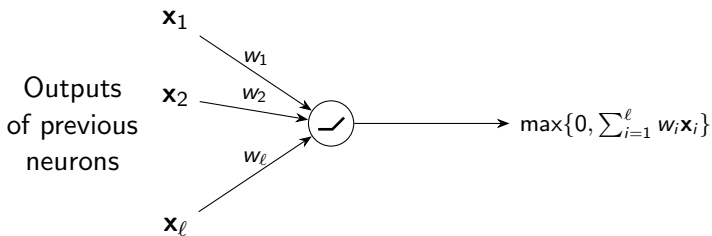
(both problems have broader context ...)



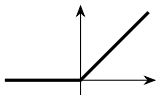
# A Single ReLU Neuron



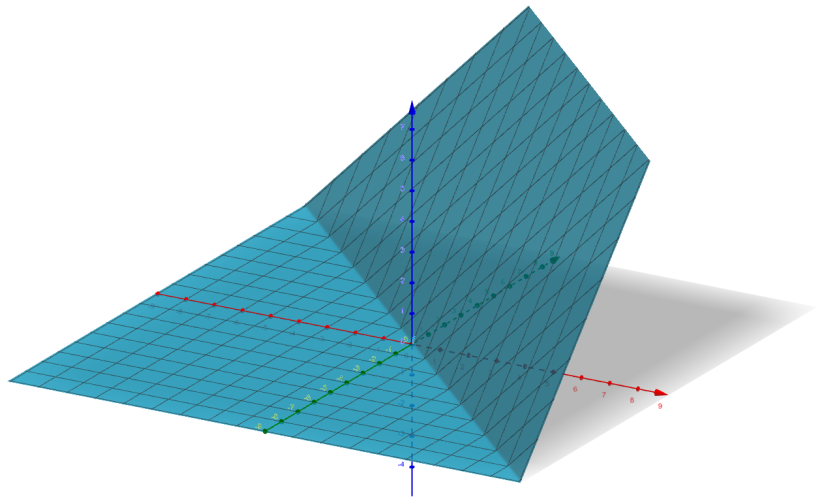
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Rectified linear unit (ReLU):  $\text{relu}(x) = \max\{0, x\}$

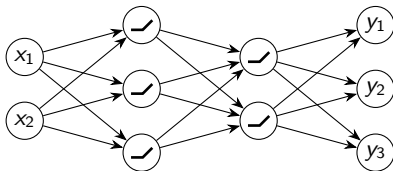


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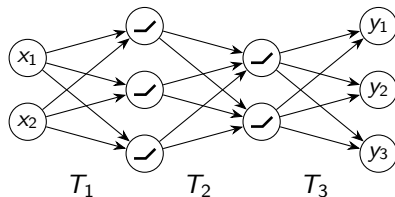
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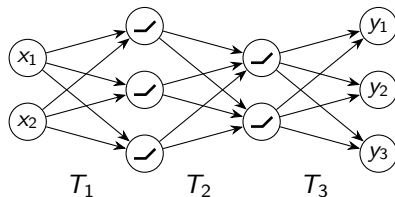
- ▶ Computes function

$$T_k \circ \text{relu} \circ T_{k-1} \circ \cdots \circ T_2 \circ \text{relu} \circ T_1$$

with linear transformations  $T_i$ .

# ReLU Feedforward Neural Networks

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with linear transformations  $T_i$ .

- ▶ Example: depth 3 (2 hidden layers).

# NNs and CPWL Functions

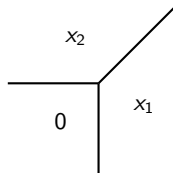
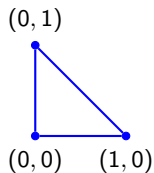
Theorem (Arora, Basu, Mianjy, Mukherjee (ICLR 2018))

*$f: \mathbb{R}^n \rightarrow \mathbb{R}$  can be represented by a ReLU NN if and only if  $f$  is continuous and piecewise linear (CPWL).*

# Support Functions and Newton Polytopes

## Definition

The *support function*  $f_P$  of a polytope  $P \subseteq \mathbb{R}^n$  maps a cost vector  $x \in \mathbb{R}^n$  to the objective value of the linear program  $\max_{v \in P} x^T v$ .

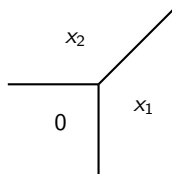
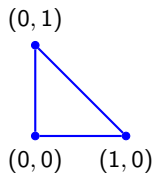




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## Definition

The *Newton polytope* of a convex CPWL function

$f(x) = \max\{v_1^T x, v_2^T x, \dots, v_p^T x\}$  is  $P(f) = \text{conv}\{v_1, v_2, \dots, v_p\}$ .

# Bijection between Convex CPWL Functions and Polytopes

Have a bijection between these two sets:

- ▶ Convex CPWL functions  $\mathbb{R}^n \rightarrow \mathbb{R}$ ,
- ▶ Polytopes in  $\mathbb{R}^n$ .

The bijection maps ...

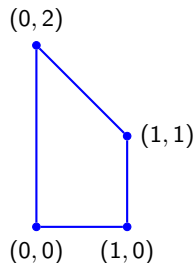
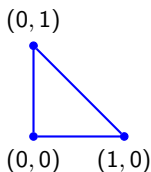
- ▶ Functions to their Newton polytope  $f \mapsto P_f$ ,
- ▶ Polytopes to their support function  $P \mapsto f_P$ .

## Adding Two (Convex) CPWL Functions

$$\begin{aligned}\max\{0, x_1, x_2\} + \max\{0, x_2\} &= \max\{0, x_2, x_1, x_1 + x_2, x_2, 2x_2\} \\ &= \max\{0, x_1, 2x_2, x_1 + x_2\}\end{aligned}$$

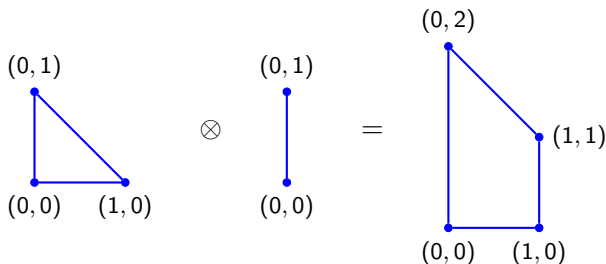
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► Minkowski sum:  $P \otimes Q := \{p + q \mid p \in P, q \in Q\}$ ,

## The Bijection is a Semigroup Isomorphism

$$P_{f+g} = P_f \otimes P_g,$$

$$f_{P \otimes Q} = f_P + f_Q.$$

(Convex CPWL functions  $\mathbb{R}^n \rightarrow \mathbb{R}$ , +)

$\cong$

(Polytopes in  $\mathbb{R}^n$ ,  $\otimes$ )

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**YES!**

↪ Virtual Polytopes!

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In the same way:

- ▶ **Virtual Polytopes** =  $\{\frac{P}{Q} = P \oslash Q \mid P, Q \subseteq \mathbb{R}^n \text{ polytopes}\}$



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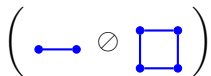
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- ▶ Remember:  $\frac{a}{b} = \frac{c}{d} \Leftrightarrow ad = bc$
- ▶ In the same way:  $\frac{P}{Q} = \frac{R}{S} \Leftrightarrow P \otimes S = Q \otimes R$

(formally via equivalence relations)

## Two Examples

Cancellation Rule:



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$$\left( \text{---} \circlearrowleft \square \right) = \left( \cdot \circlearrowleft \text{---} \right)$$

The diagrammatic equation shows two sides of an equality. On the left side, a horizontal blue line with two dots at its ends is followed by a circle containing a diagonal slash, which is then followed by a blue square with four dots at its corners. On the right side, a single blue dot is followed by a circle containing a diagonal slash, which is then followed by a vertical blue line with two dots at its ends. The entire equation is enclosed in large parentheses.

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$$\left( \text{---} \ominus \text{□} \right) = \left( \bullet \ominus \text{I} \right) = \text{I}^{\otimes -1}$$

Adding two virtual polytopes:

$$\left( \text{△} \ominus \text{□} \right) \otimes \left( \text{△} \ominus \text{---} \right)$$

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$$\begin{aligned} & \left( \triangle \circlearrowleft \square \right) \otimes \left( \triangle \circlearrowleft \text{---} \right) \\ &= \left( \triangle \otimes \triangle \right) \circlearrowleft \left( \square \otimes \text{---} \right) \\ &= \left( \text{---} \circlearrowleft \square \right) \otimes \left( \triangle \circlearrowleft \text{---} \right) \end{aligned}$$



## Two Examples

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## We even have a Group Isomorphism!

(CPWL functions  $\mathbb{R}^n \rightarrow \mathbb{R}$ ,  $+$ )

$\cong$

(Virtual Polytopes in  $\mathbb{R}^n$ ,  $\otimes$ )

In particular:

Every CPWL function is a difference of two convex CPWL functions.

$$\frac{P}{Q} \mapsto f_P - f_Q$$

$$f - g \mapsto \frac{P_f}{P_g}$$

# Virtual Polytopes are Almost Polytopes

- ▶ They have a **face lattice**,
  - ▶ faces are virtual polytopes.
- ▶ They have a **volume**,
  - ▶ but volume can be negative.

# The General Idea

Find out which **virtual polytopes**  
can occur as **Newton polytopes** of **CPWL functions**  
computed by **neural networks** of a certain size (or structure).

## Which Operations can NNs perform?

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- ▶ Scalar multiplication
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## We even have a Vector Space Isomorphism!

$$f = \max_{i=1}^p \{v_i^T x\} \quad \Rightarrow \quad P_{\lambda f} = \text{conv}_{i=1}^p \{\lambda v_i\} = \lambda P_f$$

(CPWL functions, +, scalar multiplication)

$\cong$

(Virtual Polytopes,  $\otimes$ , scaling)

(for  $\lambda < 0$  also consistent with Minkowski difference)



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- ▶ Taking Maxima ?

## “Maximum” for Two Virtual Polytopes

For two convex CPWL functions  $f$  and  $g$ :

$$P_{\max\{f,g\}} = \text{conv}\{P_f \cup P_g\} =: P_f \oplus P_g.$$

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For  $f = f_+ - f_-$  and  $g = g_+ - g_-$  (non-convex) CPWL functions.

$$\begin{aligned}\Rightarrow \max\{f, g\} &= \max\{f_+ - f_-, g_+ - g_-\} \\ &= \max\{f_+ + g_-, g_+ + f_-\} - (f_- + g_-).\end{aligned}$$

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Translating to **virtual** polytopes:

$$\begin{aligned}P_f \oplus P_g &:= P_{\max\{f,g\}} \\ &= \frac{(P_{f_+} \otimes P_{g_-}) \oplus (P_{g_+} \otimes P_{f_-})}{(P_{f_-} \otimes P_{g_-})}\end{aligned}$$

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Does this remind you of something?  $\rightsquigarrow \frac{a}{b} + \frac{c}{d} = \frac{ad+bc}{bd}$

## We also have a Semiring Isomorphism!

$$\begin{aligned} &(\text{CPWL functions, } \max, +) \\ &\cong \\ &(\text{Virtual Polytopes, } \oplus, \otimes) \end{aligned}$$

(here you see the “tropical” world!)



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- ▶ Scalar multiplication  $\leftrightarrow$  Scaling of (virtual) polytopes ✓
- ▶ Taking Maxima  $\leftrightarrow$  convex hull of the union ✓

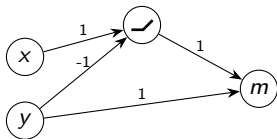
# Take a Breath!

Now to the two open problems:

- ▶ Can 3-layer NNs compute the maximum of 5 numbers?
- ▶ Can poly-size NNs solve the MST problem?

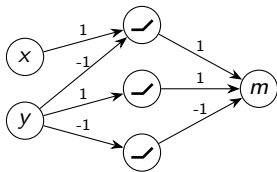
## Computing the Maximum of Two Numbers

$$\max\{x, y\} = \max\{x - y, 0\} + y$$

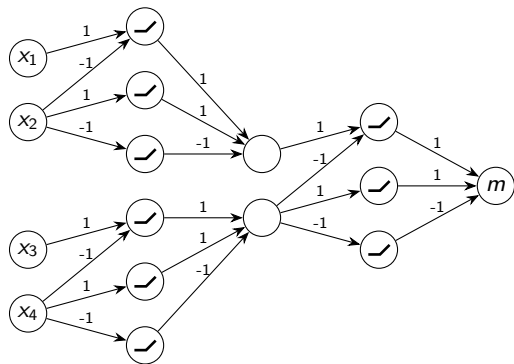


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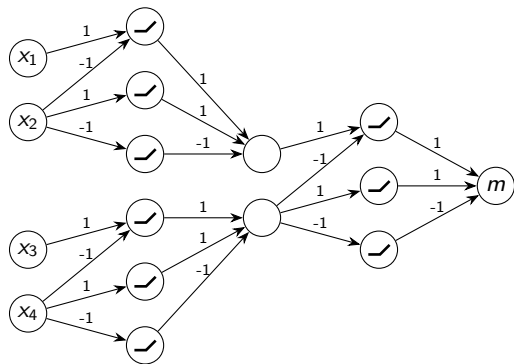
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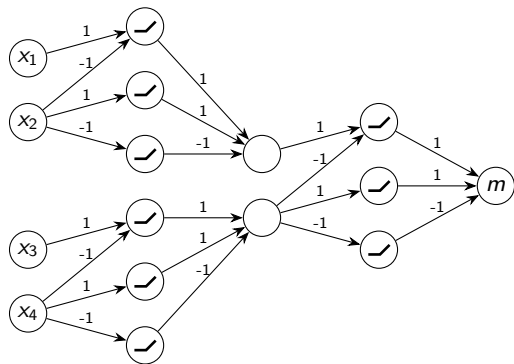


## Computing the Maximum of Four Numbers



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**Question:** Is this best possible?



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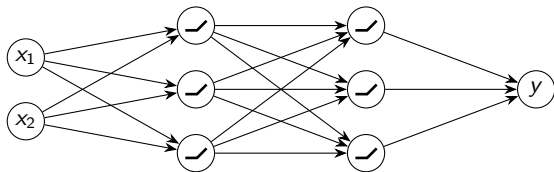
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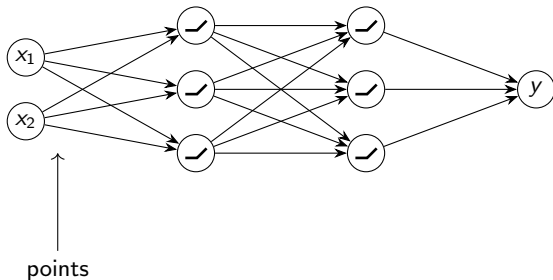
### **That's all!**

- ▶ No function known that provably needs more than 3 layers.
- ▶ Smallest open case:  
Can  $\max\{0, x_1, x_2, x_3, x_4\}$  be computed with 3 layers?

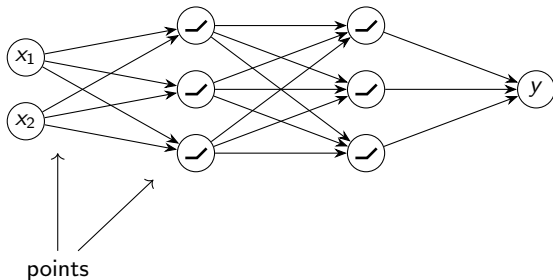
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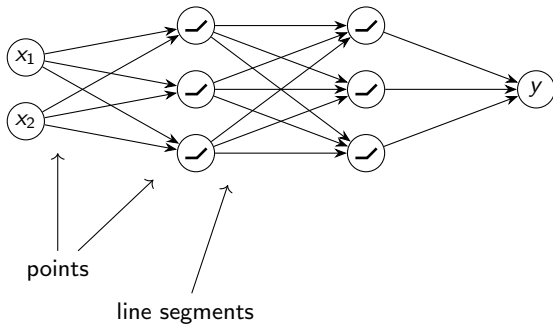


# Virtual Newton Polytopes of Neural Networks

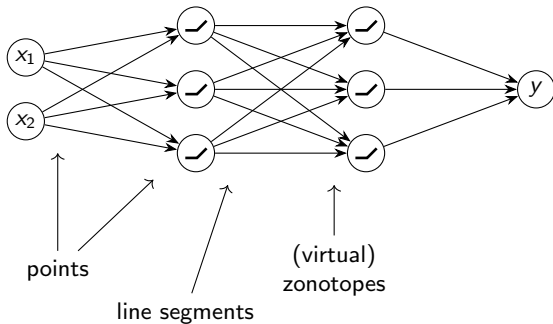




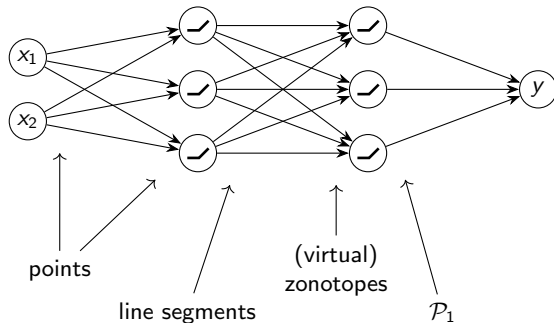
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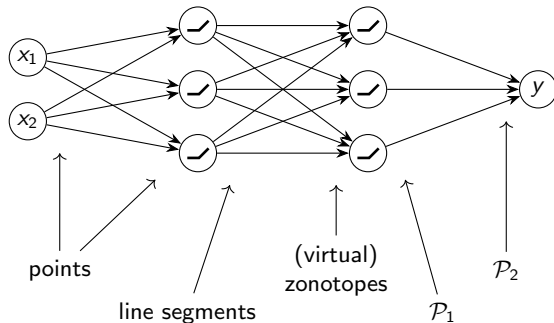
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(convex hull of the union of two zonotopes)

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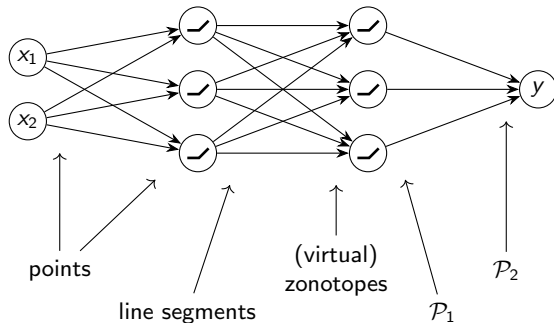


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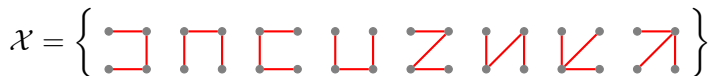
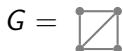
$f(x) = \max\{0, x_1, x_2, x_3, x_4\}$  can be computed by 3-layer NN

$$\Leftrightarrow 4\text{-simplex } \Delta^4 = P_f \in \mathcal{P}_2.$$

# The Two Open Problems

- ▶ Can 3-layer NNs compute the maximum of 5 numbers?
- ▶ Can poly-size NNs solve the MST problem?

# The Minimum Spanning Tree Problem



Let  $\mathcal{X} \subseteq \{0, 1\}^E$  be the set of characteristic vectors of spanning trees in a fixed graph  $G = (V, E)$ .

# The Minimum Spanning Tree Problem

$$G = \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ \bullet \end{array}$$

$$\mathcal{X} = \left\{ \begin{array}{cccccccc} \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \end{array} \right\}$$

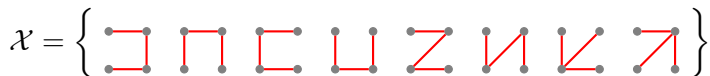
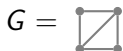
Let  $\mathcal{X} \subseteq \{0, 1\}^E$  be the set of characteristic vectors of spanning trees in a fixed graph  $G = (V, E)$ .

**MST problem:** Compute the CPWL function

$$c \mapsto \min_{x \in \mathcal{X}} c^T x.$$



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**MST problem:** Compute the CPWL function

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**Question:** Is there a poly-size NN computing this function?

Is there a poly-size NN to solve MST?

$$f(c) = \min_{x \in \mathcal{X}} x^T c = - \max_{x \in \mathcal{X}} (-x)^T c$$

$$\Rightarrow P_f = \text{conv}\{-x \mid x \in \mathcal{X}\}^{\otimes -1} = (-\text{MST-Polytope})^{\otimes -1}$$

## Is there a poly-size NN to solve MST?

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### Proposition

*There exists a poly-size NN computing  $f$*

$\Leftrightarrow$

*The MST-Polytope can be (virtually) generated from points via polynomially many operations of the form*

- ▶ *Minkowski addition,*
- ▶ *Convex hull of the union,*
- ▶ *Scaling (with possibly inverting).*

Thank you!

$$\left\{ \begin{array}{c} x_2 \\ \text{---} \\ 0 \\ \text{---} \\ x_1 \end{array} \right\} \cong \left\{ \begin{array}{c} (0, 1) \\ \text{---} \\ (0, 0) \quad (1, 0) \end{array} \right\}$$

Questions? Ideas?